

# Large Aperture "Photon Bucket" Optical Receiver Performance in High Background Environments

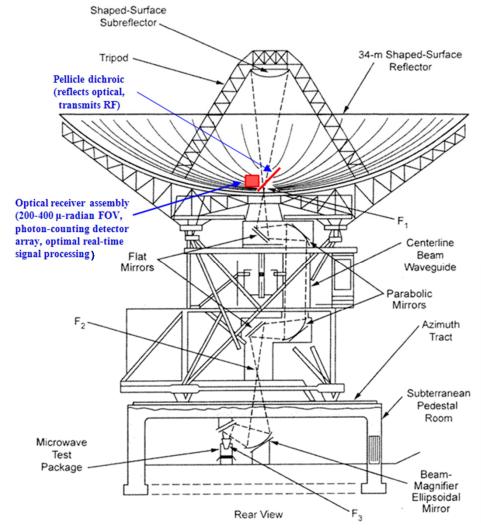
V. Vilnrotter, D. Hoppe

Jet Propulsion Laboratory
California Institute of Technology

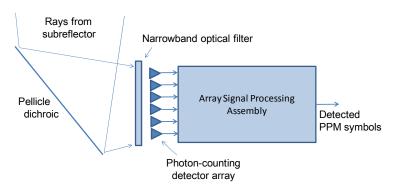


#### Polished Panel System Concept

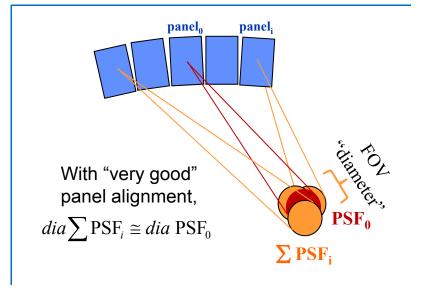
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Optical communications receiver assembly placed at F1: RF/Optical dichroic, optical filter, detector array, high-speed signal-processing equipment.



Functional block diagram of Optical Receiver Assembly, placed on the main reflector at F1, near the entrance to the RF beam waveguide in a DSN 34-meter antenna.





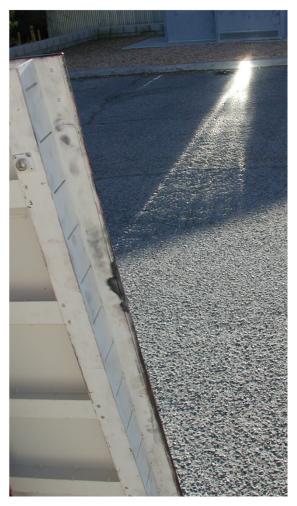
## **Initial Polished Panel Experiments**

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## DSN polished panel, initial daytime visual tests



DSN polished panel reflectivity, surface accuracy test

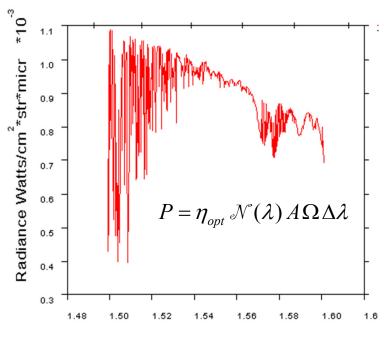


DSN polished panel ray concentration



#### Background Radiation and Polished Panel PSF

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Wavelength Microns Example of sky radiance for a desert model, at "sun-earth-probe" (SEP) angle of 10 degrees.

$$\Omega = \pi R^{2} / f_{eff}^{2}$$

$$n_{b} = \eta_{opt} \eta_{d} \pi R^{2} \mathcal{N}(\lambda) A \Delta \lambda / h v f_{eff}^{2}$$

$$K_{b} = \eta_{opt} \eta_{d} \mathcal{N}(\lambda) A \Omega \Delta \lambda \tau / h v \equiv I_{b} A$$

Average background count  $K_b$  depends on background intensity in photo-counts/meter<sup>2</sup>, and collecting area A in meter<sup>2</sup>

 $\mathcal{N}(\lambda)$ 

 $\boldsymbol{A}$ 

Ω

Spectral radiance functionReceiver collecting area

- Receiver FOV, steradians

 $\lambda$ 

- Optical signal wavelength

 $\Delta \lambda$ 

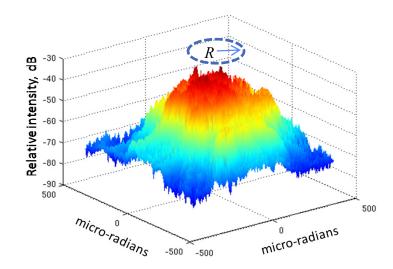
- Narrowband filter bandwidth

 $\eta_{opt}$ 

- Optical system throughput

 $\eta_{\scriptscriptstyle d}$ 

- Detection efficiency

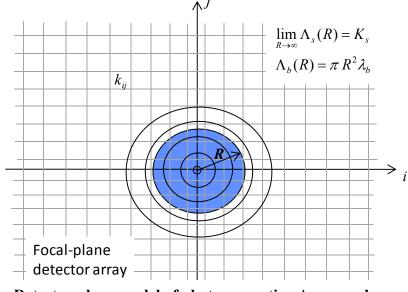


Example of PSF generated by a realistically modeled panel surface error distribution, showing high concentration of signal energy in the inner +/- 125 micro-radians from center. Horizontal axes in  $\mu$ rads, vertical axis in dB (intensity, arbitrary units)



#### Focal-Plane Spatial Filter Optimization

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Poisson calculation:

$$P_{M}^{l}(C) \ge \sum_{k=1}^{\infty} \frac{\left(\Lambda_{s}(R) + \Lambda_{b}(R)\right)^{k}}{k!} \exp\left[-\left(\Lambda_{s}(R) + \Lambda_{b}(R)\right)\right] \times \left\{\sum_{k=1}^{k-1} \frac{\left(\Lambda_{b}(R)\right)^{j}}{k!} \exp\left[-\left(\Lambda_{b}(R)\right)\right]\right\}^{M-1}$$

$$P_M^u(E) \equiv 1 - P_M^l(C) \ge P_M(E) \cong P_M(E)$$

Detector-plane model of photon-counting Array and PSF with small pointing offsets.

Gaussian approximation: 
$$P_M(C) \cong \int dy \, Gs$$

Gaussian approximation: 
$$P_{M}(C) \cong \int_{-\infty}^{\infty} dy \, Gsn[\Lambda_{s}(R) + \Lambda_{b}(R), y] \left[ \int_{-\infty}^{y} dx \, Gsn[\Lambda_{b}(R), x] \right]^{M-1}$$

- Laser transmitter appears as a point source, therefore ...
- Average signal count can be expressed as:  $K_s = I_s A$
- With fixed field-of-view  $\Omega$ , the average background count can be expressed as:  $K_b = I_b A$

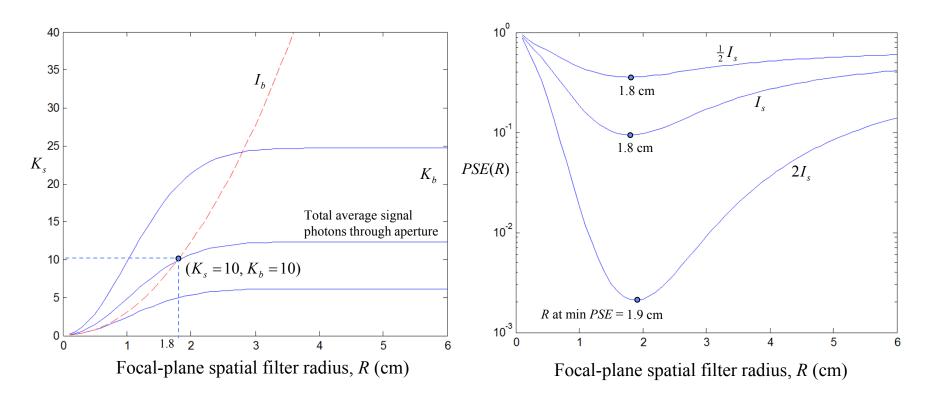
$$\Delta K_{s} = I_{s} \Delta A$$

$$\Delta K_b = I_b \, \Delta A = (I_b / I_s) \Delta K_s$$

Focal-Plane Spatial Filter Optimization

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## Focal-plane optimization with constant background intensity

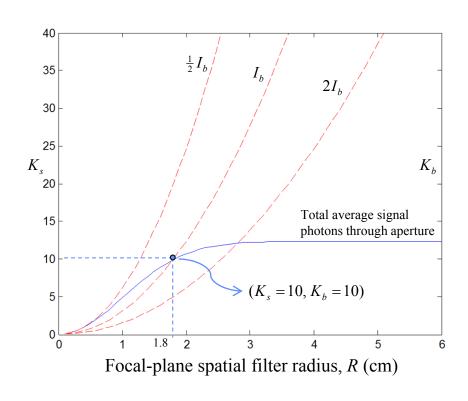


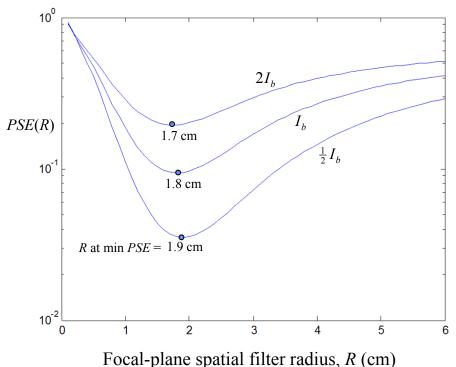
2D Gaussian PSF model, standard deviation  $\sigma_{PSF} = 1 \text{ cm}$ 

Focal-Plane Spatial Filter Optimization

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## Focal-plane optimization with constant signal intensity



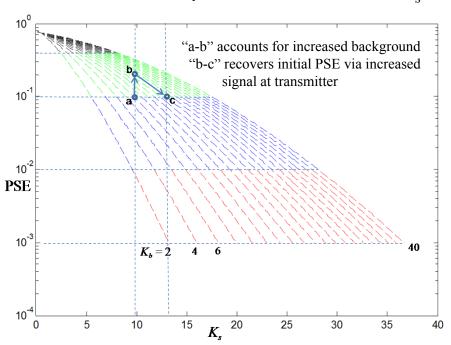


2D Gaussian PSF model, standard deviation  $\sigma_{PSF} = 1 \text{ cm}$ 

#### Computation of Constant PSE Contours

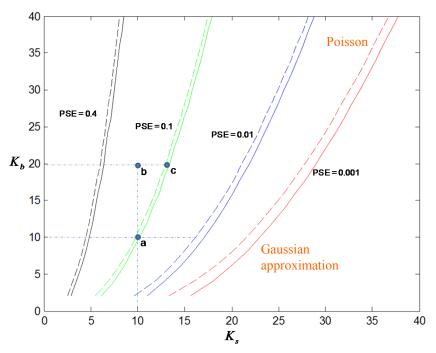
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## Poisson computation of PSE vs $K_s$



Probability of symbol error, PSE, for M = 4 PPM signaling as a function of  $K_s$ , for a range of background energies,  $K_b$ .

## Constant PSE contours, $(K_s, K_b)$ plane

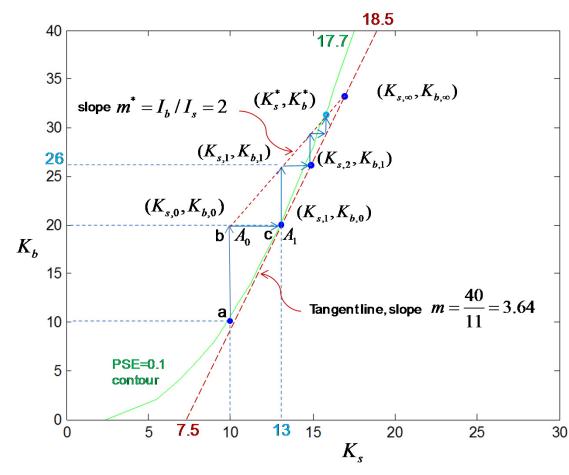


Contours of constant symbol-error probability, PSE, over the  $(K_s,K_b)$  plane. Dashed curves were computed using Poisson probabilities, solid curves computed via the faster Gaussian approximation.



#### Tangent-Line Approximation and Exact Solution

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Compensation for excess background energy by increasing signal energy via aperture expansion, with the goal of maintaining constant symbol-error probability of 
$$PSE = 0.1$$
.

$$K_{s,1} = K_{s,0} + \Delta K_{s,1} = I_s (A + \Delta A_1)$$

$$K_{b,1} = K_{b,0} + \Delta K_{b,1} = I_b (A + \Delta A_1)$$

$$= \frac{I_b}{I_s} (K_{s,0} + \Delta K_{s,1})$$

$$K_{s,2} = K_{s,0} + \Delta K_{s,1} + \frac{I_b}{I_s m} \Delta K_{s,1}$$

$$K_{s,3} = K_{s,0} + \Delta K_{s,1} + \frac{I_b}{I_s m} \Delta K_{s,1} + \left(\frac{I_b}{I_s m}\right)^2 \Delta K_{s,1}$$

$$K_{s,\infty} = K_{s,0} + \Delta K_{s,1} \sum_{k=0}^{\infty} (I_b / I_s m)^k$$

$$= K_{s,0} + \Delta K_{s,1} (1 - \frac{I_b}{I_s m})^{-1}$$

$$= K_{s,0} + \Delta K_{s,1} \alpha / (\alpha - 1); \quad \alpha = I_s m / I_b$$

Similarly for 
$$K_b$$
:  $K_{b,\infty} = (I_b/I_s)K_{s,\infty}$   
for  $\alpha > 1$  since  $\lim_{\alpha \to 1} \alpha/(\alpha - 1) = \infty$ 



Tangent-Line Approximation and Exact Solution

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Example: 
$$K_{b,0} = 20$$
,  $K_{s,0} = 10$ ,  $\Delta K_{s,1} \cong 3$ ,  $\Delta K_{b,1} \cong 6$ ,

$$m = 40/11 = 3.64$$

$$\alpha/(\alpha-1)=2.22$$

$$K_{s,\infty} = 10 + 6.67 = 16.67$$
  $K_{b,\infty} = 2K_{s,\infty} = 33.3$ 

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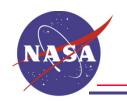
$$(K_{s,i}, K_{b,i}), \quad i = 0, 1, 2, \dots \qquad m^* = I_b / I_s$$

$$m^* = I_b / I_s$$

$$(K_s^* = 15.5, K_b^* = 31.5)$$

$$\Delta A \cong 55\%$$
  $\Delta D \cong 24\%$ 

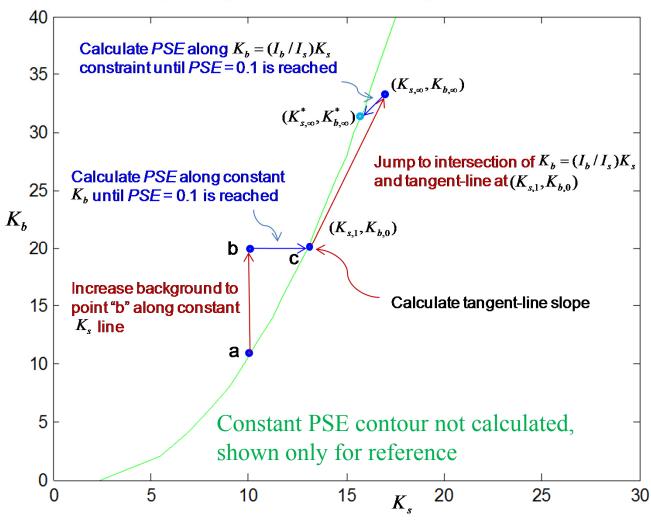
Therefore, only 55% increase in receiver collecting area (or 24% increase in receiver diameter) is required to compensate for 100% increase in background energy.



### Reduced Complexity Algorithms

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## Proposed "simpler" algorithm for calculating final $(K_s, K_b)$ values



#### **Reduced Complexity Algorithms**

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# Other potential "simpler" algorithms

- 1. Gaussian approximation:
- Compute PSE contour using the Gaussian approximation
- Determine intersection of  $K_b = (I_b / I_s) K_s$  line with Gaussian contour
- Calculate *PSE* along  $K_b = (I_b / I_s) K_s$  constraint
- 2. Constrained trajectory solution:
- Starting at (0,0) calculate PSE along the  $K_b = (I_b/I_s)K_s$  trajectory using Poisson model until desired PSE is reached

Evaluation and Comparison of Reduced Complexity Algorithms remains the subject of future work